# **MODEL SUPB TRANSDUCER**

The SUPB is a heavy-duty transducer designed to accurately measure web tension in machines having liveshaft idler rolls. One is placed under the pillow block bearing on each end of a roll shaft. The SUPB has no hinges so it is more reliable and stronger than other UPB transducers on the market. It works equally well with both live and dead shaft idlers. The SUPB transducer is designed to measure forces which are mostly perpendicular to the top plate.

It is available in eight load ratings: 100, 200, 400, 800, and 1200 for Size 2, and 1000, 2500, and 5000 lbs for Size 3.

# **BENEFITS/FEATURES**

- Low maintenance design lifetime lubricated.
- Sensitive to loads perpendicular to the top plate.
- Corrosion-resistant stainless steel and aluminum construction.
- Entire length of top plate is clear for pillow block installation only along center line.

# **OPTIONS** -

- Extended Range output (XR). Produces twice the output signal for a given load rating. Must be used with electronics having extended range option.
- Environmental Connector (EC). Prevents liquid from entering transducer through the connector. Especially useful in corrosive environments.
- Full Bridge (FB). Four strain gauges in only one transducer instead of two. Wheatstone Bridge configuration. Used only when a single SUPB is used.

The transducer can be mounted in any angular orientation about the roll axis. It is designed for use with the tension force direction ' $F_{T}$ ' within +\- 45° of perpendicular to the transducer top plate (see diagram 2). Outside of this angular range, DFE's model UPBH transducer should be used. The UPBH transducer is used to measure tension with the applied force directed mostly parallel to the topplate.

- Can be installed in any orientation.
- 360 degree overload stop.
- Splash resistant.
- Load ratings to 5000 lbs.
- Use with live or dead shaft idler rolls.
- Permanently Attached Cable (PT). Permanently attached cable instead of amphenol connector.
- Permanently Attached Cable with Connector (PTC).
- **Right Angle Connector (RAB)**. Allows electrical connector to plug in at 90° angle.

# PRODUCT CODE

You may order by description or by specifying the code by matching each labeled place with one of the choices below. **Example: SUPB2-100-S-EC,XR** 

SUPB		- XXX	(-X-	· OPTIONS				
	ļ	ļ	ļ	Ļ				
	SIZE	LOAD RATING	CONNECTOR POSITION	OPTIONS				
	2 = Size 2 3 = Size 3	100 lb. <sup>1</sup> 200 lb. <sup>1</sup> 400 lb. <sup>1</sup> 800 lb. <sup>1</sup> 1000 lb. <sup>2</sup> 1200 lb. <sup>1</sup> 2500 lb. <sup>2</sup> 5000 lb. <sup>2</sup>	S = Standard O = Optional <sup>1</sup>	DT = Drill and Tap EC = Environmental Connector XR = Extended Range <sup>4</sup> FB = Full Bridge <sup>3</sup> PT = Permanently Attached Cable PTC = Permanently Attached Cable with connector RAB = Right Angle Connector <sup>1</sup> Z = Special (SPR)				

NOTES: 1. Available on Size 2 only.

2. Available on Size 3 only.

3. Applies only if one transducer is used.

4. Controller / Indicator must have XRE option

# SELECTION OF LOAD RATING

To select the correct load rating for an SUPB transducer you will need to calculate Net Force from Roll Weight and Net Force from Tension. The sum of these net force components equals the Total Net Force used to select the correct load rating.

 $F_T$  = direction of force midway between two tensions

- V = line 'V', perpendicular to mount surface and top plate
- **1.** Enter values from your application for the equation variables below.
  - T = max. tension in web
  - W = weight of roll and support bearings
  - A = angle between weight 'W' direction and line V
  - B = web wrap angle (= $180^{\circ}$  C in diagram 2)
  - $D = angle between tension force direction FT and line V_____.$

# **Dimensional Constants** inches (mm)

 $\frac{\text{Size 2}}{\text{L} = 2.4 (61)} \qquad \qquad \frac{\text{Size 3}}{4.5 (11)}$ 

L = 2.4 (61) $H = 1.5 (38) + a^*$   $3.0 (76) + a^*$ 

\* $\mathbf{a} = 1.0 (25.4)$  to 2.5 (63.5) 1.5 (38.1) to 2.5 (63.5)

\*Where " a " is the idler roll shaft center height from the top plate surface.

 Refer to the Diagram 1 formulas for Net Force from Roll Weight. Determine whether the roll weight will be pushing toward or pulling away from the top plate, and whether the direction of the weight from the center of the roll is pointed in the 90° quadrant on the left or the right of line V (observe the pivot end marked "P"). Plug the values for your variables (and the dimensional constants) into the associated equation that most closely matches your application. Calculate the Net Force from Roll Weight. *Note:* It is critical to maintain the algebraic sign ("+" or "-") in the result. If the Net Force from Roll Weight is more than 95% of the load rating chosen, the tension meter will probably not be adjustable to zero. If this is the case, one or more of the following changes must be made.

- Reduce the transducer weight.
- Decrease Angle A.
- Use the next higher load rating. Please consult DFE for advice.

 Refer to the Diagram 2 formulas for Net Force from Tension. Select the drawing that most closely matches your application in terms of F<sub>T</sub> direction relative to line V (observe the pivot end marked "P"). Note: When the calculated Net Force from Tension is negative (i.e. pulling away from the transducer) it is necessary to reverse the signal polarity in associated electronics (indicators or controllers). This optional reverse polarity can be specified when purchasing DFE electronics.

4. Add the Net Force from Weight and the Net Force from Tension paying close attention to the algebraic sign of each component. Use the total to select the appropriate load rating (lbs) from the list below.

Size	Max. Net Force Ibs. (Newtons)	Load Rating				
	up to 120 (550 N)	100 lbs. (450 N)				
2	240 (1075 N)	200 lbs. (900 N)				
2	480 (2150 N)	400 lbs. (1800 N)				
	960 (4275 N)	800 lbs. (3600 N)				
	1440 (6425 N)	1200 lbs. (5350 N)				
	up to 1200 (5350 N)	1000 lbs (4450 N)				
3	3000 (13350 N)	2500 lbs (11125 N)				
	6000 (26700 N)	5000 lbs (22250 N)				

# DIAGRAM 1: FORMULAS FOR NET FORCE FROM ROLL WEIGHT

For weight acting in this

90°quadrant of transducer

WEIGHT NET FORCE =

(+) [W] [Lcos(A) + Hsin(A)]

2L

CASE A: Weight pushing toward top plate

W

ν

PIVOT END STAMPED '

For weight acting in this

90° quadrant of transducer

WEIGHT NET FORCE =

(+) [W] [Lcos(A) - Hsin(A)]

2L



CASE B: Weight pulling away from top plate

NOTE: When the transducer is mounted horizontally, the Weight Net Force equations can be simplified to W / 2 in CASE A, and (-) W / 2 in CASE B.

# **DIAGRAM 2: FORMULAS FOR NET FORCE FROM TENSION**

#### Note:

If FT is perpendicular (Angle D = 0°, i.e. sinD = 0.0) and toward the top plate, either of the two drawing/formulas on the left can be used.

If FT is perpendicular (Angle  $D = 0^\circ$ , i.e. sinD = 0.0) and pulling away from the top plate, either of the two drawing/formulas on the right can be used.

With wrap type 2 or 3 there will be no output if angle  $D = 45^{\circ}$ , and there will be a reversal of signal polarity for angles greater than  $45^{\circ}$ .

For wrap 1 or 4, as angle D increases beyond 45°, tension sensitivity decreases.

WRAP 1 <u>FT **pushes toward** top plate and away **from** pivot end</u>



TENSION NET FORCE = (+) [4Tsin(B/2)] [Lcos(D) + Hsin(D)] 2L





TENSION NET FORCE = (+) [4Tsin(B/2)] [Lcos(D) - Hsin(D)] 2L

] Angle	ABLE 1	
(Degrees)	SINE	COSINE
0	.000	1.000
5	.087	.996
10	.1/4	.985
15	.259	.966
20	.342	.940
20	.423	.900
35	.500	819
40	.643	.766
45	.707	.707
50	.766	.643
55	.819	.574
60	.866	.500
65	.906	.423
70	.940	.342
80	.900	.239
85	996	087
90	1.000	.000



FT pulls from the top plate and away from pivot end



TENSION NET FORCE = (-) [4Tsin(B/2)] [Lcos(D) - Hsin(D)] 2L





#### TENSION NET FORCE = (-) [4Tsin(B/2)] [Lcos(D) + Hsin(D)] 2L

# **SPECIFICATIONS**

# **ELECTRICAL**

### **Excitation:**

5 Vdc, regulated (10Vdc with XR)

### **Output:**

250 mVdc, nominal, at 5V excitation (500 mVdc at 10V excitation with XR)

# Strain Gage Resistance:

100 ohms, nominal

#### **Non-Repeatability:** ±1/4% Full Span (FS)

# **Combined Non-Linearity and Hysteresis:**

 $\pm 1/2\%$  (FS)

# **Temperature range:**

-10°F to 200°F (-23°F to 93°C)

### **Mating Electrical Connector:**

3-Pin Amphenol with Clamp (DFE #721-1445)

# **Electrical Connector Position:**

Refer to Dimension drawing on back page

# **BEARING RECOMMENDATION**

The SUPB transducer will perform best if the proper bearings are used.

First, both of the bearings should have **self-aligning** capability. This will eliminate stresses on the top plate caused by roll deflection, misalignment and uneven mounting surfaces.

Second, the shaft should be able to "**float**" (move axially a small amount) relative to one of the bearings to compensate for roll/shaft length expansion.

# **MECHANICAL**

#### Deflection: Size 2 = 0.010 in. max. (0.3 mm) Size 3 = 0.015 in. max. (0.4mm)

### Load ratings:

Size 2 = 100, 200, 400, 800, 1200 lbs. (450, 900, 1800, 3600, 5350 N) Size 3 = 1000, 2500, 5000 lbs. (4450, 11125, 22250 N)

### Static Overload Capacity:

Size 2 = 3,000 lbs. (13,000 N) Size 3 = 10,000 lbs. (44,000 N)

### Material:

303, 304 Stainless Steel, 7075-T6 Aluminum;

### **Load Direction:**

+/- 45° of perpendicular to top plate

### Weight:

Size 2 = 9 lbs. (4 kg.) Size 3 = 30 lbs. (14 kg.)

SIZE		Α	В	С	D	Е	F	Н	K	L	М	N	0	Ρ	R	S
2	in.	2.62	9.00	2.88	2.62	3.80	0.45	8.00	8.00		0.53	1.36	0.95	4.54	1.31	0.56
	mm	67	229	73	67	96	11	203	203		14	34	24	115	33	14
3	in.	4.50	13.5	5.74	4.12		0.94	12.25	11.25	2.75	0.53	2.97	1.65	6.82		0.94
	mm	114	343	146	105		24	311	286	70	14	75	42	173		24

# DIMENSIONS

Note: Connector position is on long side for Size 2, and pivot end for Size 3



Figure below for Size 2 SUPB's only.



- "P" Denotes Pivot End of Transducer
- "S" Denotes Standard Connector Position
- "O" Denotes Optional Connector Position

